

# Model theoretic approaches to Szemerédi's regularity lemma

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# Regularity of a graph

## Definition (Graph)

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## Theorem (Informal Szemerédi regularity lemma)

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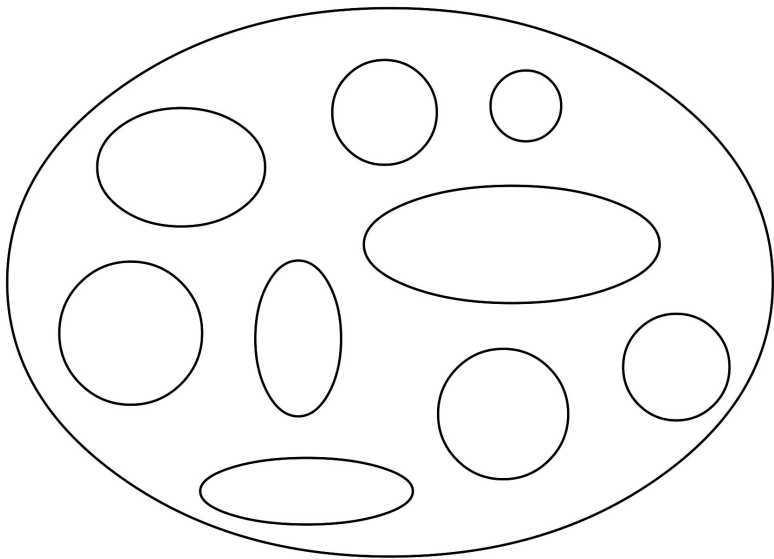
*The vertex set of every finite graph can be partitioned into a “bounded” number of parts so that the graph looks “random-like” between “most” pairs of parts of the partition.*

## Definition (Edge density)

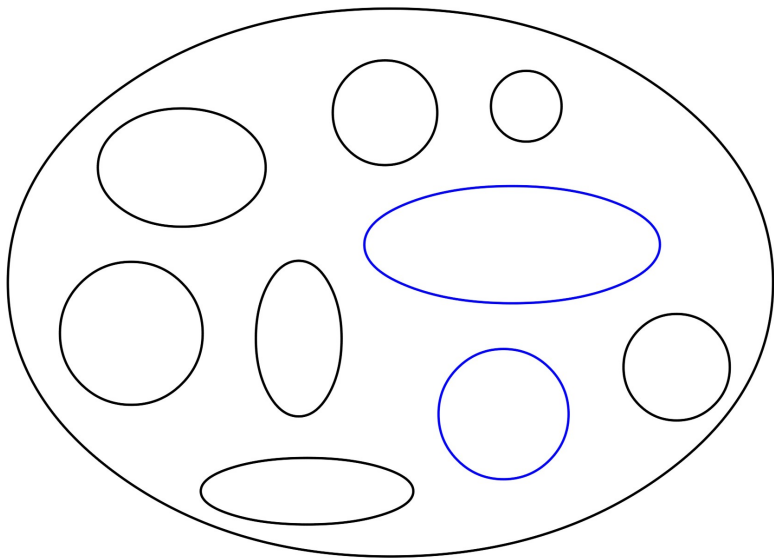
Define the **edge density** between  $X$  and  $Y$  in  $G = (V, E)$  by

$$d(X, Y) := \frac{|E(X, Y)|}{|X||Y|}.$$

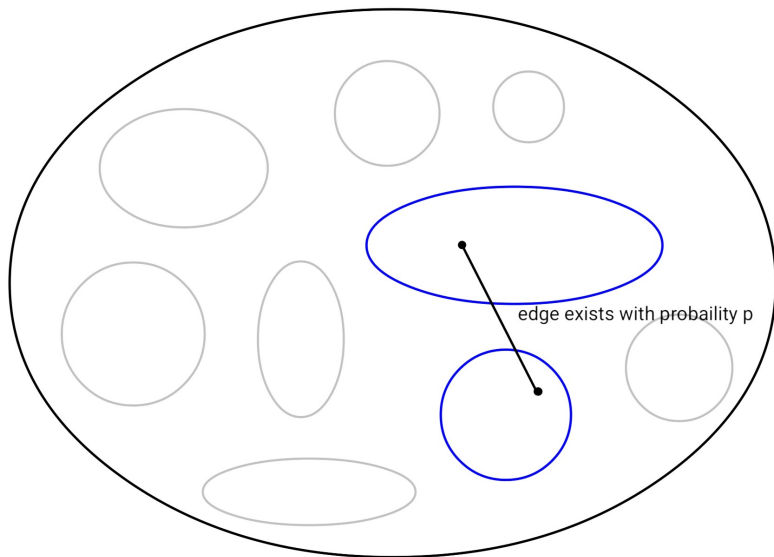
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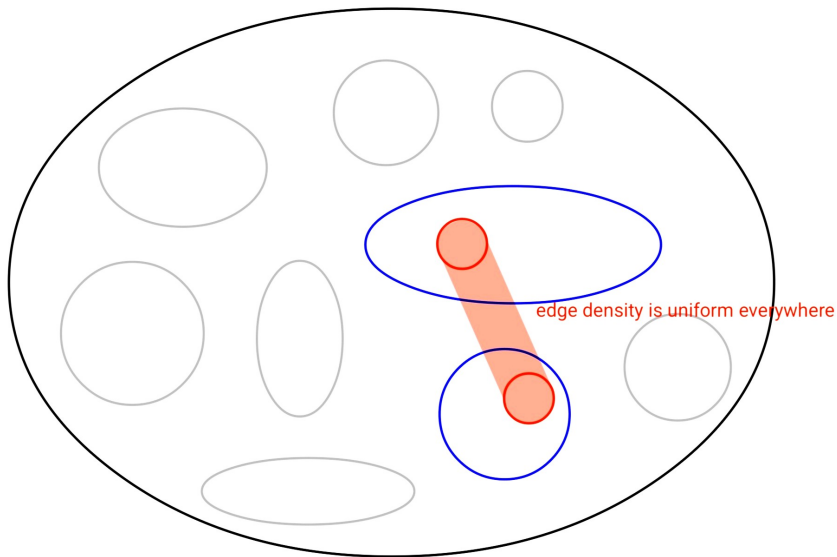
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Random-likeness in terms of edge density can be reformulated as follows:  
Local edge density is always almost the same as the global edge density  
(which should be true if a graph is “truly random”).

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# Stable graphs

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## Definition (half graph)

- 1 A  **$k$ -half graph** is a graph  $V = \{a_0, \dots, a_{k-1}, b_0, \dots, b_{k-1}\}$  satisfying:

For any  $i, j < k$ ,  $E(a_i, b_j)$  if and only if  $i < j$ .

- 2 A graph not containing a  $k$ -half graph is called a  **$k$ -stable** graph.

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## Remark

It is a localized and finitized notion of the central notion of model theory, stability.

# Stable regularity lemma

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*The vertex set of every  $k$ -**stable** graph can be partitioned into a “bounded” number of parts (depending on  $k, \epsilon$ ) so that the graph looks **almost empty or complete** between **all** pairs of parts of the partition.*

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**Question: Can we derive the theorem also for finite graphs?**

## Definition (Filter)

Let  $\mathcal{F}$  be a family of subsets of  $\omega$ .  $\mathcal{F}$  is called a **filter** on  $\omega$  if

- $\emptyset \notin \mathcal{F}$ ,
- if  $A, B \in \mathcal{F}$ , then  $A \cap B \in \mathcal{F}$ , and
- if  $A \in \mathcal{F}$  and  $A \subseteq B \subseteq \omega$ , then  $B \in \mathcal{F}$ .

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## Definition (Ultrafilter)

If  $\mathcal{F}$  is a filter and  $A$  or  $\omega \setminus A$  belongs to  $\mathcal{F}$  for any  $A \subseteq \omega$ , then it is called an **ultrafilter** on  $\omega$ .

## Notation

- ① For any finite tuple  $\bar{a} = a_0 a_1 \cdots a_{n-1} \in (\prod_{i \in \omega} M_i)^n$ ,  $\bar{a}[i]$  is the projection to the  $i$ -th coordinate of  $\omega$ :

$$\bar{a}[i] = a_0[i] a_1[i] \cdots a_{n-1}[i] \in (M_i)^n.$$

- ② For any finite tuples  $\bar{a}, \bar{b} \in (\prod_{i \in \omega} M_i)^n$ ,  $\bar{a} \sim_{\mathcal{U}} \bar{b}$  if  $\{i : \bar{a}[i] = \bar{b}[i]\} \in \mathcal{U}$ .

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## Theorem (Łoś Theorem)

*Let  $\{M_i : i \in \omega\}$  be a sequence of  $\mathcal{L}$ -structures and  $\mathcal{U}$  be an ultrafilter on  $\omega$ . Then for any  $\mathcal{L}$ -formula  $\varphi(\vec{x})$  and any finite tuple  $\vec{a}$  in  $\mathfrak{M}$ ,*

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- Ultraproducts can give good notions of limits.

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- 1 Suppose that the desired theorem for finite graphs is not true, then we can get a sequence of finite graphs that witness the failure of the theorem.

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- 3 Apply a “useful fact” on the infinite or continuous objects to get a useful fact on the definable sets of the ultraproduct.
- 4 Use Łoś Theorem to show that this useful fact on the definable sets also holds for almost every finite graph in the sequence.
- 5 Point out that this useful fact is contradictory to the failure of the theorem for finite graphs. □

# Concluding remarks

In fact, we can say more in the stable regularity lemma.

## Theorem (Informal stable regularity lemma)

*The vertex set of every  $k$ -**stable** graph can be partitioned into a  $f(k) \cdot \mathbf{polynomial}(\epsilon)$  number of parts so that the graph looks **almost empty or complete** between **all** pairs of parts of the partition.*

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- It can build a bridge between finite and infinite structures; theorems on finite suggest that there is an analogue for infinite, and vice versa.
- When we are interested only on the existence of some number, then the method of ultraproduct is not defective.
- Using ultraproducts, we can forget about numeric computations and reveal that there is more “theoretic” reason why the theorem holds.

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